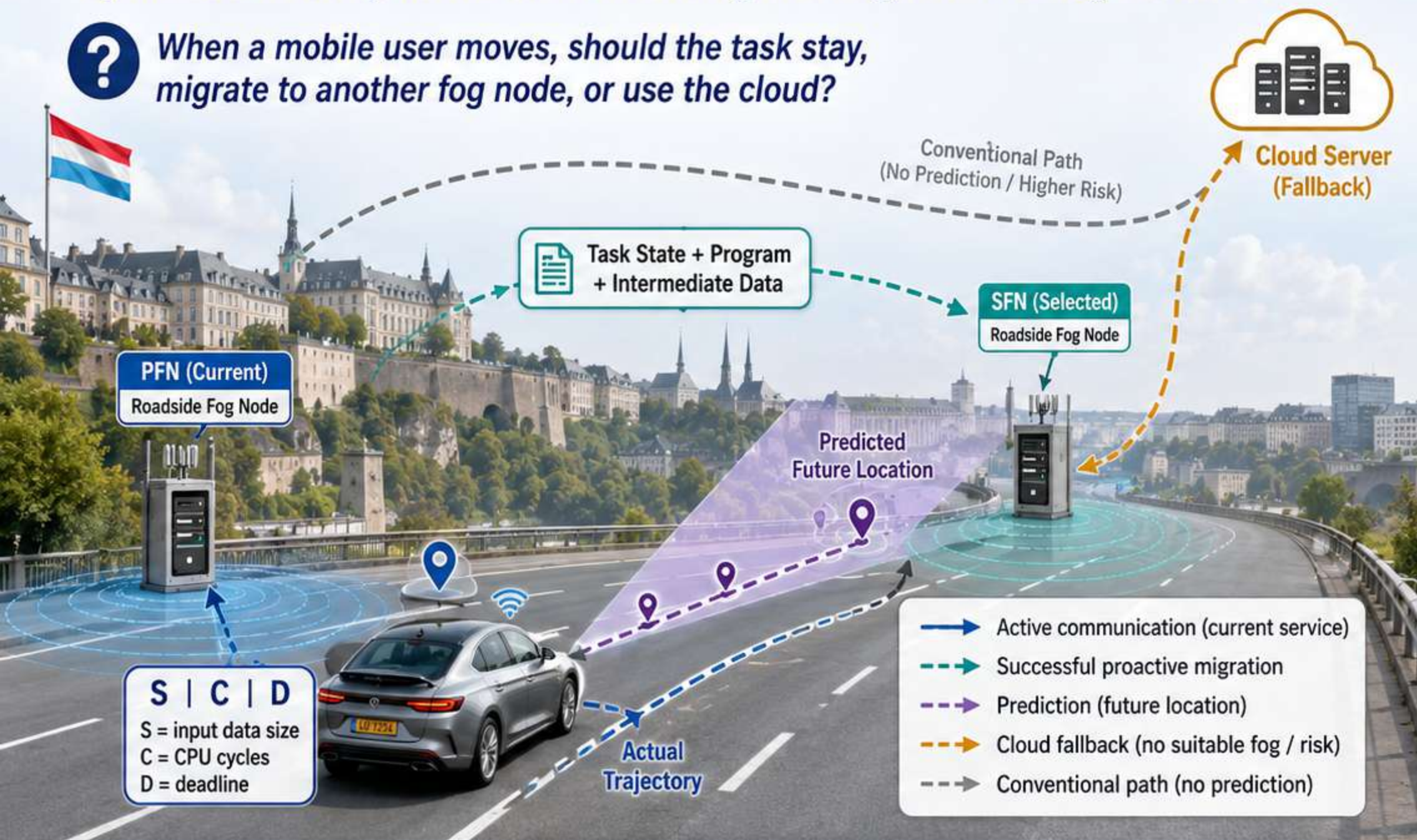


OptFog: Predict Mobility Before Migrating the Task

Optimized mobility-aware task offloading and migration for fog networks

? When a mobile user moves, should the task stay, migrate to another fog node, or use the cloud?



Where will the user be when the task still needs service?

Predict first. Migrate only when moving the task improves service continuity.

HIGHLIGHTS OF THE PAPER

01



PREDICTIVE MIGRATION ASSISTANCE:

OptFog predicts a mobile device's future location before deciding whether a running task should migrate.

02



THREE ML MODELS EVALUATED:

Decision Tree, Random Forest and k-NN are compared using LuST mobility traces.

03



DEADLINE- AND UTILIZATION-AWARE DECISION:

Migration considers the predicted location, task deadline, candidate-node latency and fog-node utilization.

04



EXPERIMENTAL FINDINGS:

Random Forest achieves 97.47% accuracy. OptFog reports up to 45% fewer handoffs, 42% fewer migrations, 22% lower network usage and 44.5% lower migration latency.



Dataset: mobility traces from 262 vehicles in Luxembourg.



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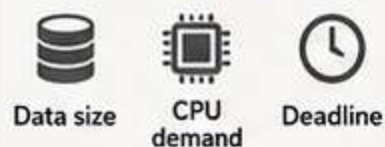
When Should a Running Task Move?

Offloading starts the task remotely; migration moves an already running task

1 Task Created

A connected vehicle / mobile end user creates a task.

Task: S | C | D



Starting choices:

Execute locally

OR

Offload to nearest PFN

2 Task Running at PFN

The PFN is processing the task. The vehicle moves away from the PFN coverage zone.



A task may still be running when the user leaves the PFN coverage area.

3 Migration Cost

Moving a running task requires state transfer and causes temporary disruption.

Migration Payload



Task State + Program + Intermediate Data

Migration Steps



Costs Incurred



Migrating too early, too late or too often wastes resources.

4 Two Strategies

Reactive or unnecessary migration



OptFog proactive migration



5 Application Trade-off

Vehicular or long-running service



Migration can preserve low-latency continuity.

Healthcare-style short request



Direct task offloading may use fewer network resources.



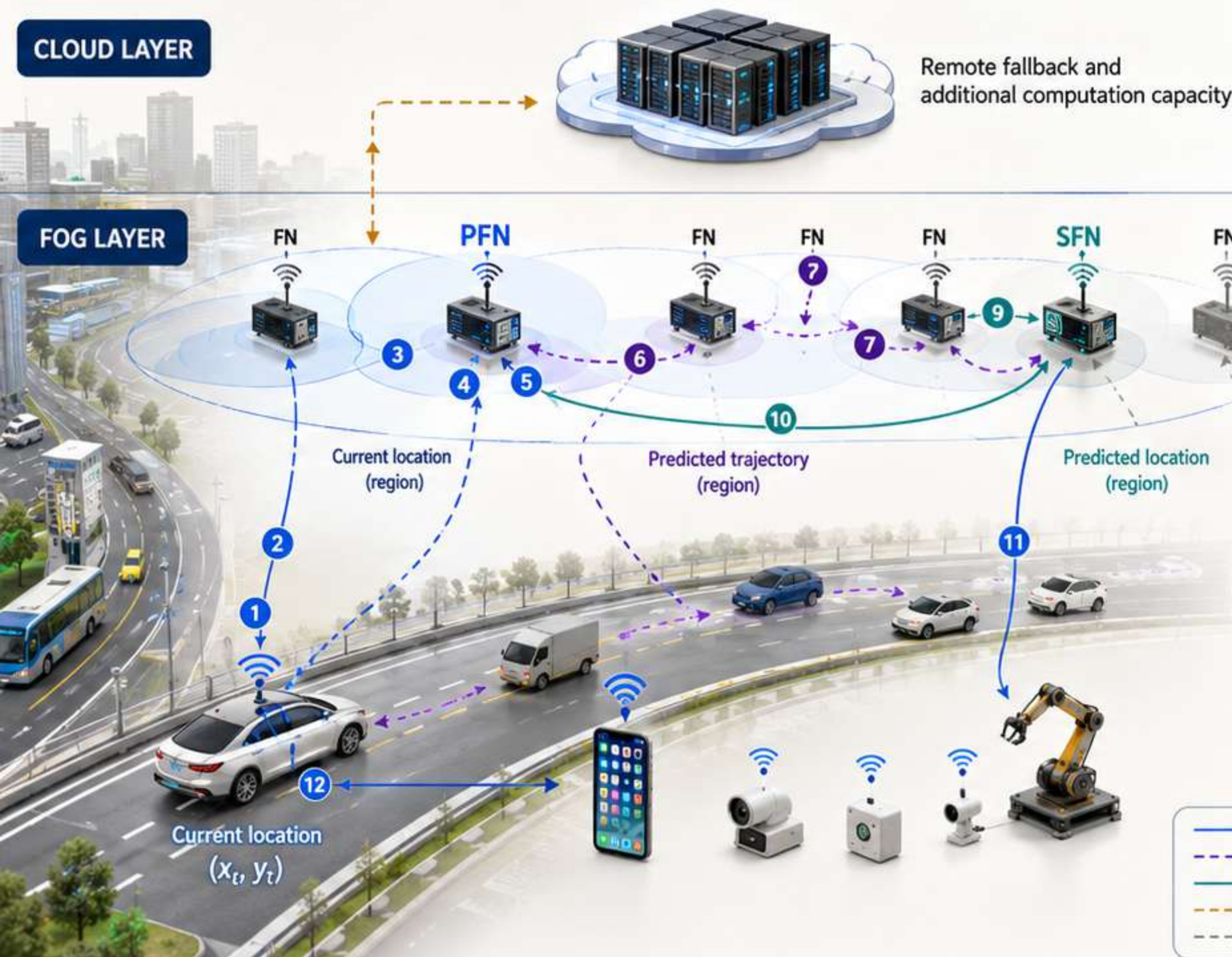
Mobility alone should not trigger migration; the system must also consider task and network conditions.

Inside the OptFog Mobility-Aware Fog Network

Predict the next location, select the next fog node, resume the task

CLOUD LAYER

FOG LAYER



RESEARCH PANEL 1 Migration Inputs

Predicted location

Deadline

Node utilization

Latency

RESEARCH PANEL 2 Task Information

Task ID

Size

CPU cycles

Deadline

Current execution time

RESEARCH PANEL 3 Decision

✓ PFN can complete? → Continue at PFN

⚖ Migration beneficial? → Move to SFN

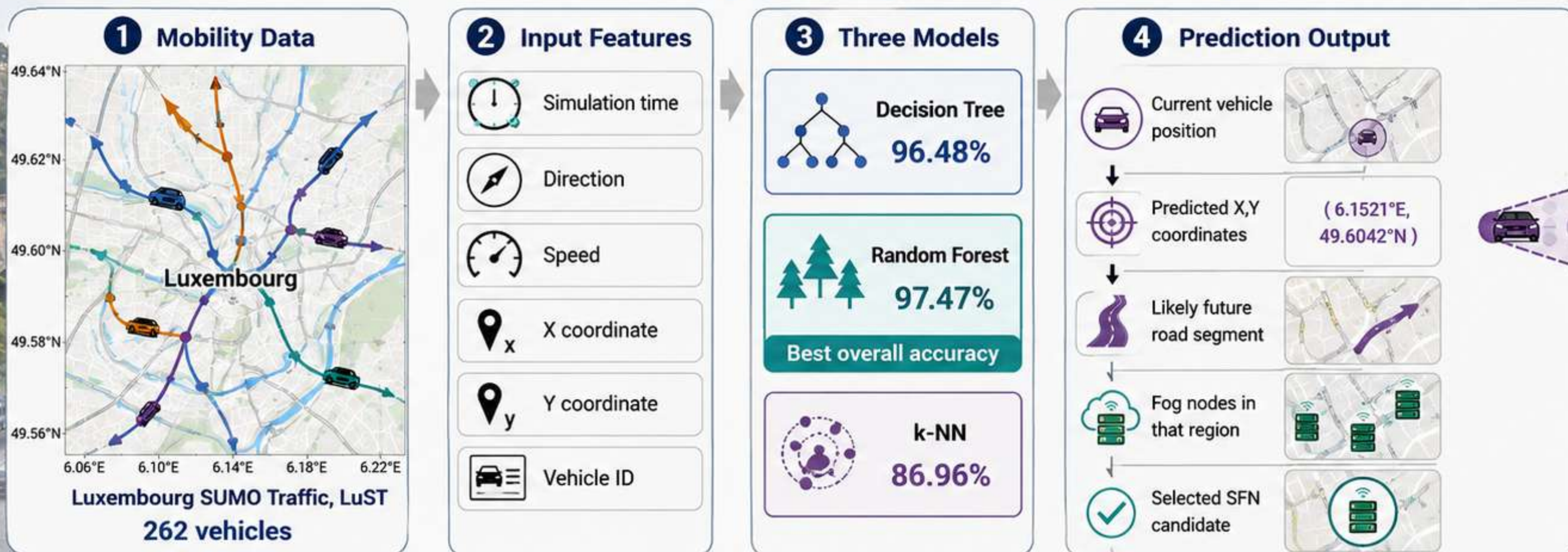
⚠ No suitable fog node? → Cloud fallback



OptFog selects the migration destination before the user reaches the next fog-node region.

Predicting the User's Next Location

LuST mobility traces guide proactive migration



5 Scientific Validation

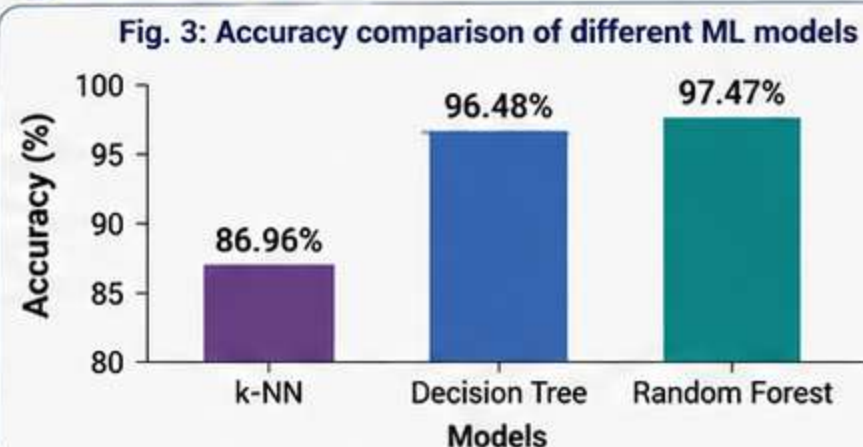
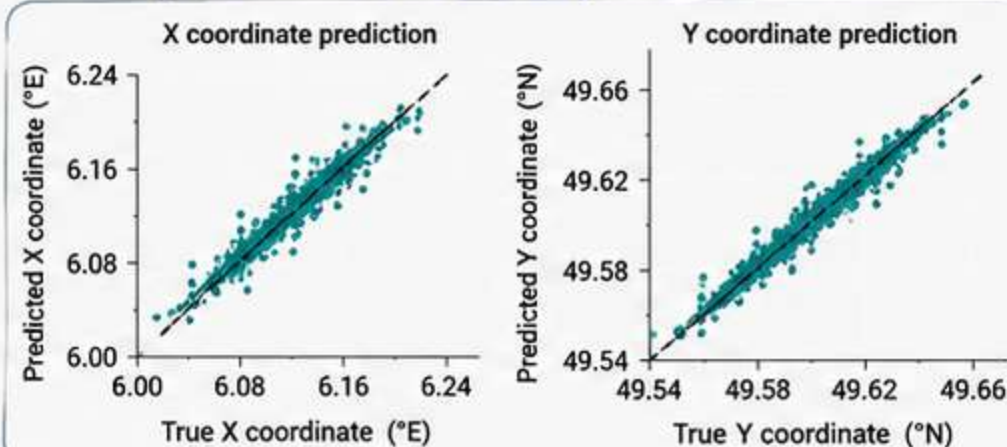


Fig. 6: Random Forest true vs predicted coordinates



The predicted location is used to search for an SFN before migration is triggered.



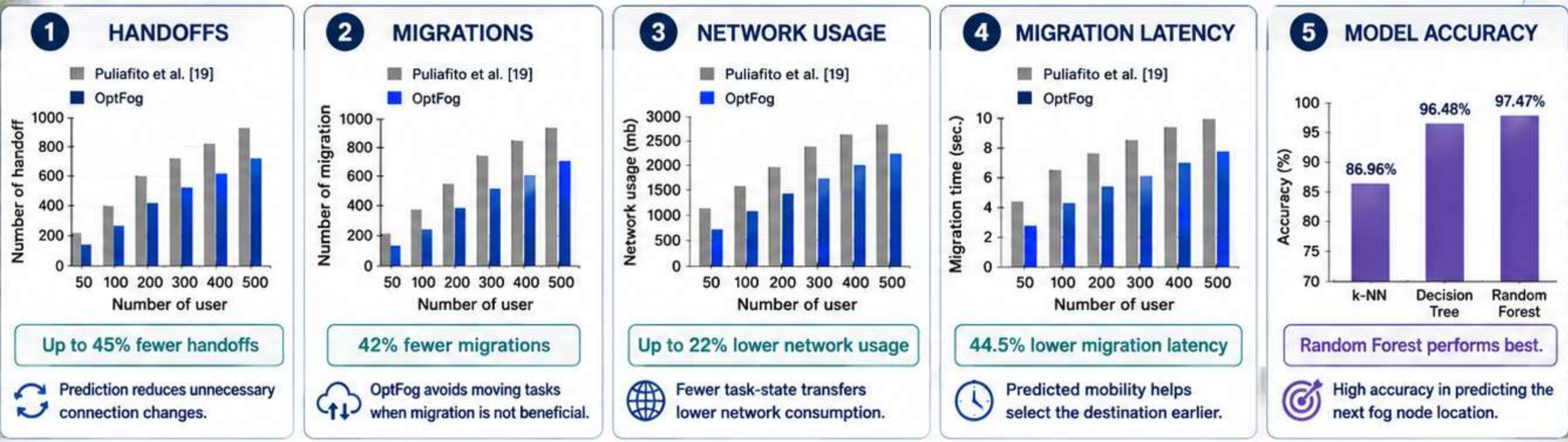
One-way ANOVA and t-tests reported *p*-values below 0.05.



More accurate location prediction enables earlier and more appropriate migration decisions.

What the OptFog Experiments Show

Prediction-based migration reduces unnecessary mobility overhead



EVALUATION SCOPE

Simulation-based using iFogSim2 and LuST mobility traces. Effectiveness is demonstrated for the evaluated vehicular mobility scenarios.

FINAL CONCLUSION

OptFog uses predicted mobility to make proactive task-migration decisions and improve mobility support in fog-assisted networks.

APPLICATION INTERPRETATION

Migration is most useful when a running service must remain close to a moving user for an extended period.

Task State + Program + Intermediate Data

PFN (current) → SFN (next)

TASK

S: Sense C: Compute D: Deliver