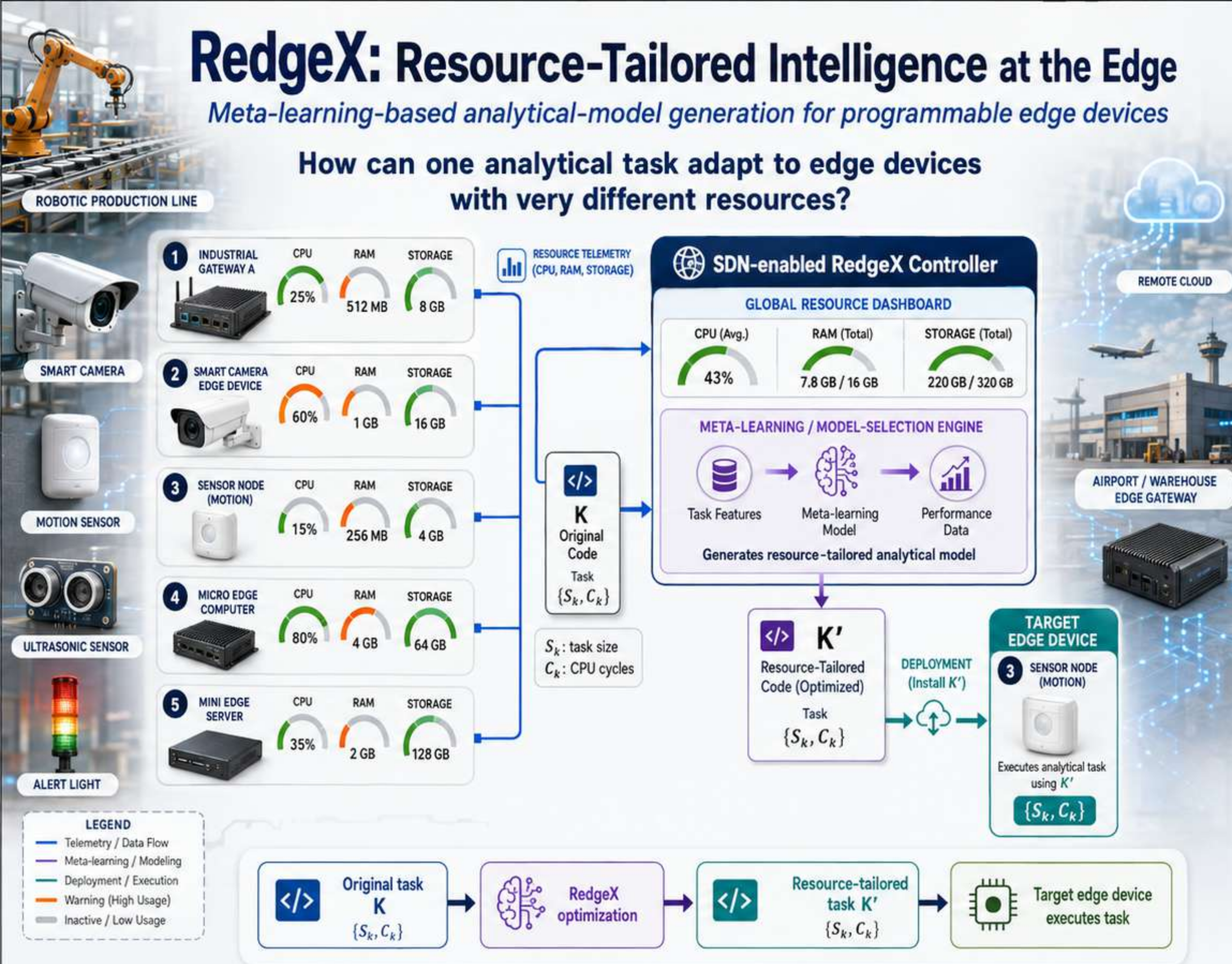


RedgeX: Resource-Tailored Intelligence at the Edge

Meta-learning-based analytical-model generation for programmable edge devices

How can one analytical task adapt to edge devices with very different resources?



HIGHLIGHTS OF THE PAPER

01



META-LEARNING MODEL GENERATION

RedgeX uses task features, edge-resource states and performance data to generate a suitable analytical model.

02



GLOBAL-STATUS EDGE CONTROL

An SDN-enabled controller maintains an updated view of CPU, RAM and storage across edge devices.

03



RESOURCE-AWARE CODE DEPLOYMENT

Original code is installed when resources are sufficient; optimized code K' is generated and deployed when resources are constrained.

04



EXPERIMENTAL FINDINGS

RedgeX reduces task-execution latency by 20–27%. The reported average gap between original and optimized code metrics is **60.6%** with Linear Regression and **61.1%** with k-NN.



Evaluated using **1,000** tuples, five edge devices and three Industrial IoT tasks.



Adapt the analytical model to the edge device instead of forcing every device to run the same code.

Different devices have different processing, memory and storage limits

1 Industrial Task



$\{S_k, C_k\}$

S_k : program + input data size

C_k : required CPU cycles

2 Heterogeneous Edge Devices

	CPU	RAM	Storage	Clock
	85%	2 GB	8 GB	1.0 GHz
	42%	4 GB	32 GB	1.6 GHz
	68%	2 GB	16 GB	1.2 GHz
	25%	8 GB	128 GB	2.4 GHz
	78%	1 GB	4 GB	0.8 GHz

?

Will the same code run efficiently on every device?

3 Original Code Sent Unchanged



4 Research Gap



Existing work mainly optimizes task offloading.

It does not select code snippets according to the current resource state of the target edge device.

$$C_k = S_k \times \rho$$

$$T_{k,n} = \frac{S_k \times \rho}{f_n}$$

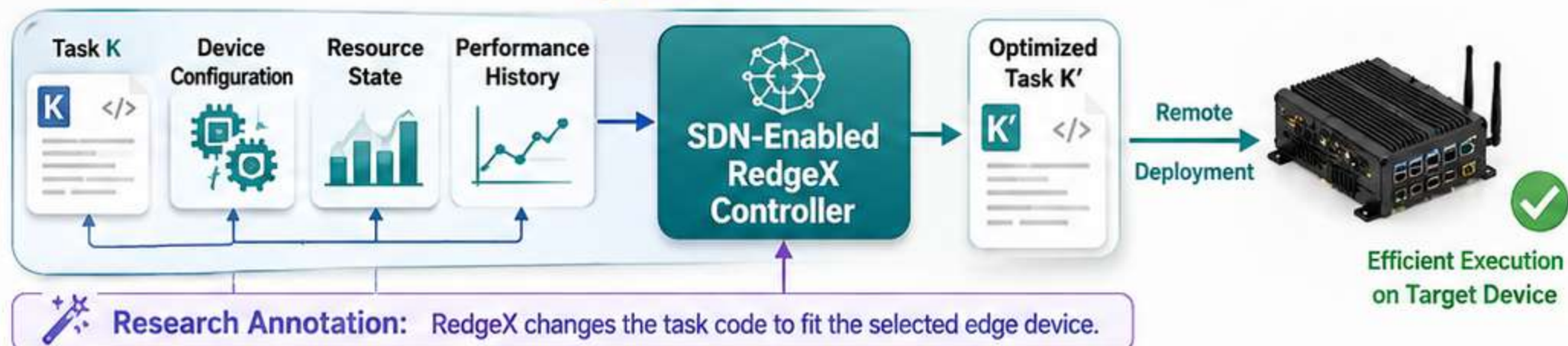
Larger tasks and slower edge CPUs require more execution time.



Research Annotation:

Fixed analytical models and manual reprogramming do not scale across heterogeneous edge networks.

5 RedgeX Idea



The problem is not only *where* to run a task, but also *which version of the task* should run there.

Inside the RedgeX Architecture

Global resource awareness and programmable task deployment

1 End device generates task $\{S_k, C_k\}$.

2 Task reaches nearest Primary Edge Node.

3 Primary node checks requirements and resources.

4 If resources are sufficient, execute original task K.

5 If resources are insufficient, send task and configuration to RedgeX Controller.

6 Controller checks global resource-status table.

7 Controller selects suitable target edge device.

8 Meta-learning creates optimized task K' when required.

9 Controller remotely installs K or K' .

10 Edge device executes task and reports updated status.

TOP LAYER — CONTROL AND CLOUD



SDN



Global Resource Dashboard



72%



61%



58%

Global State

The controller periodically collects resource information from all edge devices to support deployment and offloading decisions.

MIDDLE LAYER — COOPERATIVE EDGE NODES



CPU 65%
RAM 58%
Storage 70%
Task Status Idle
Perf. (ms) 18



CPU 48%
RAM 72%
Storage 59%
Task Status Busy
Perf. (ms) 24



CPU 81%
RAM 64%
Storage 73%
Task Status Idle
Perf. (ms) 16



CPU 55%
RAM 49%
Storage 66%
Task Status Busy
Perf. (ms) 22



CPU 67%
RAM 66%
Storage 61%
Task Status Idle
Perf. (ms) 19

BOTTOM LAYER — END DEVICES



Motion Sensor



Ultrasonic Sensor



LED Alert System



Industrial Camera



Robotic System



IoT Sensors / Actuators

Main Resource State



CPU

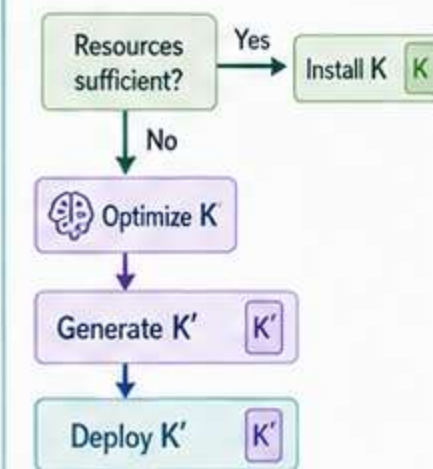


RAM



Storage

Execution Decision

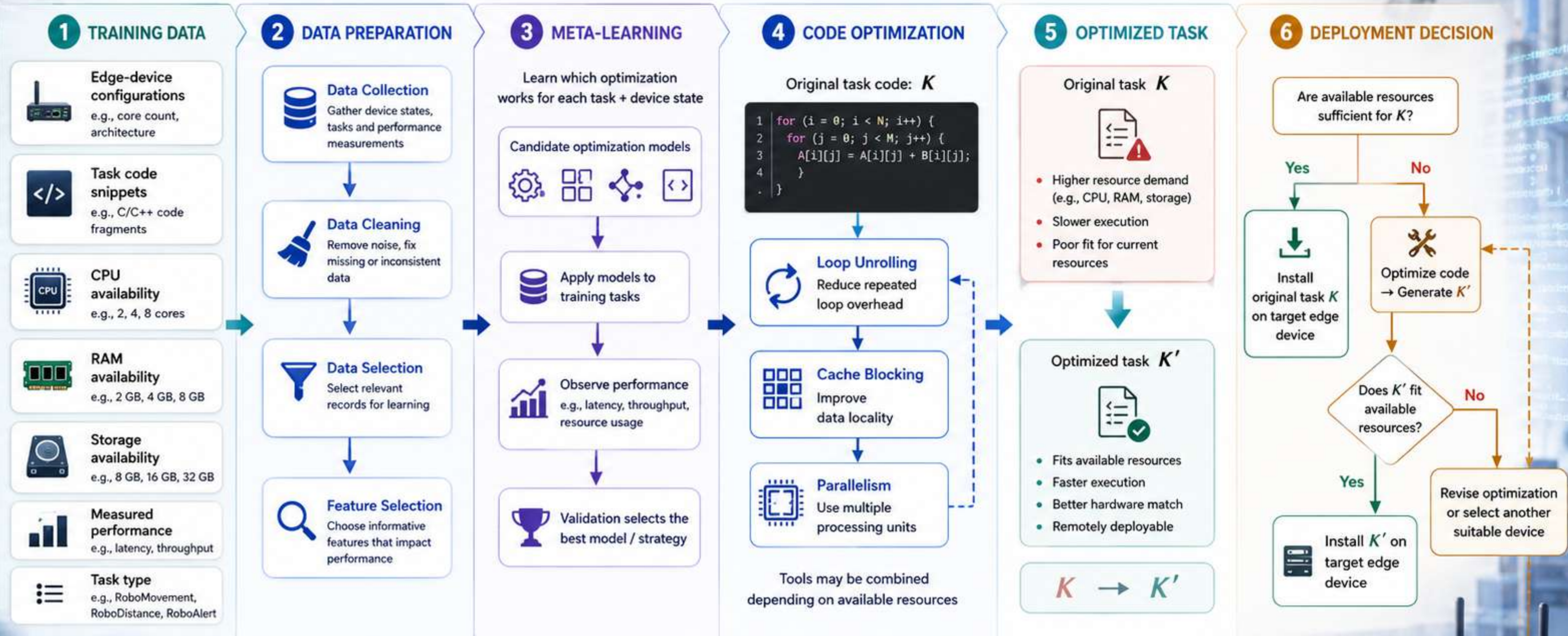


RedgeX combines edge-node selection with task-code adaptation and remote reprogramming.

K / K'

From Original Code to a Resource-Tailored Edge Task

Meta-learning selects how the analytical task should be optimized



RESEARCH ANNOTATION: The meta-learning system learns which code-optimization choices work best for different task and device configurations.

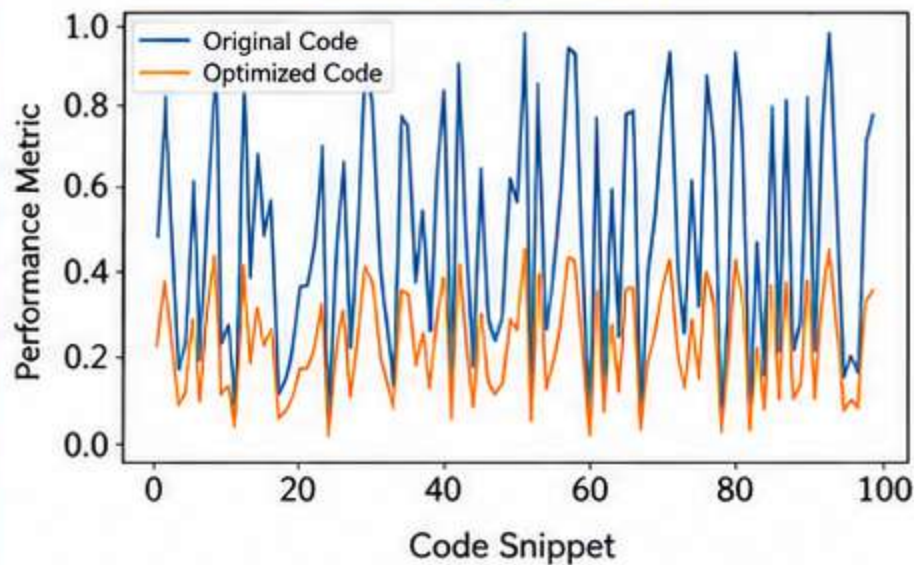


RedgeX learns how to tailor the analytical code before deploying it to the edge.

What the RedgeX Experiments Show

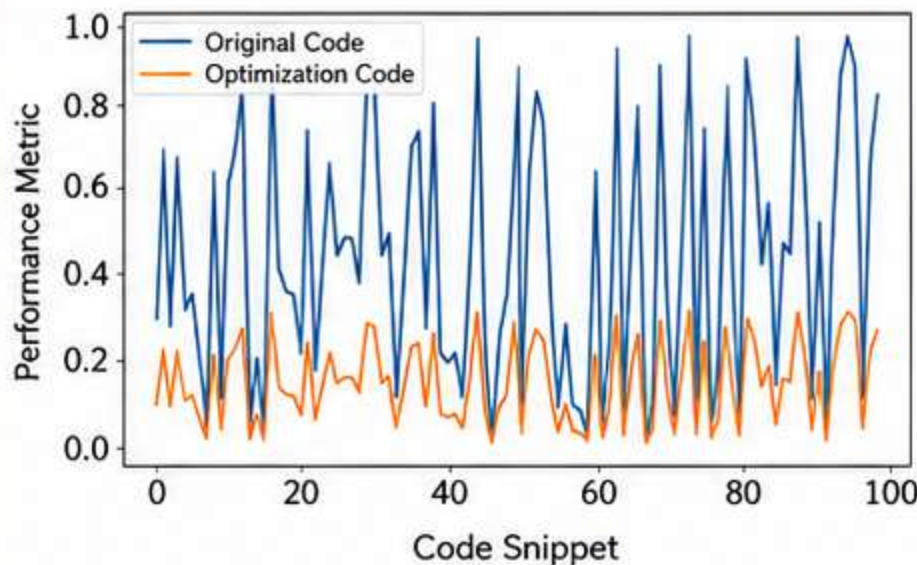
Original code versus resource-optimized edge tasks

1 Original vs Optimized Code — Linear Regression



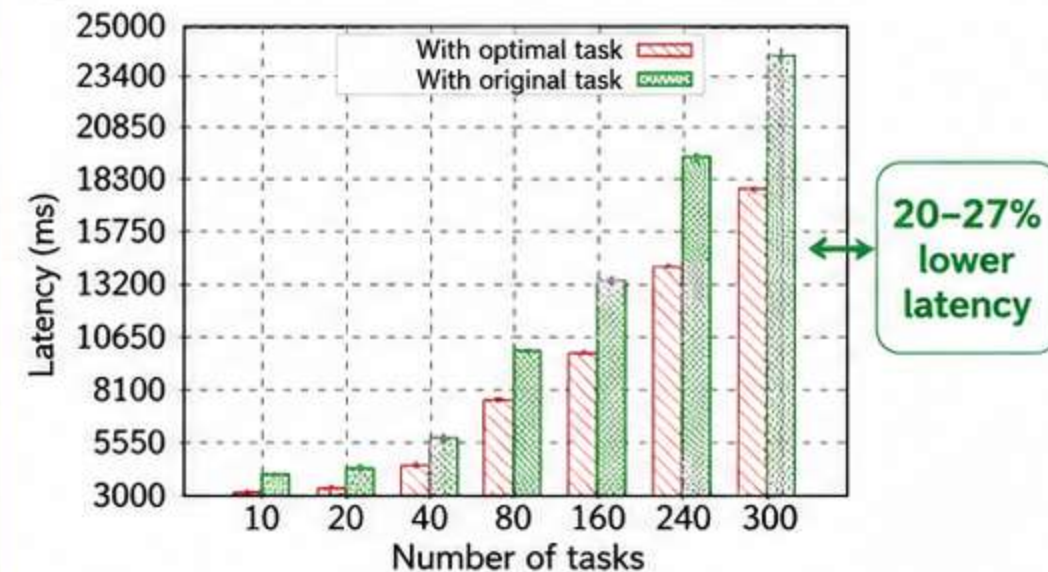
Average reported gap: **60.6%** between original and optimized task-code metrics.

2 Original vs Optimized Code — k-NN



Average reported difference: **61.1%** between original and optimized task-code metrics.

3 Task-Execution Latency



Optimized tasks reduce execution latency as the number of tasks increases.



Experimental Setup:

1,000 data tuples | 5 edge devices | 100 monitored configurations | RoboMovement | RoboDistance | RoboAlert
| Linear Regression | k-NN | REdge experimental environment



Global resource state



select suitable edge device



optimize code snippets



generate K'



remote deployment



lower execution latency



Current Evaluation Scope

The evaluation uses five edge devices and three IoT tasks. Real-life IoT edge deployment is future work.



Smart Homes



Industrial IoT



Autonomous Vehicles



RedgeX dynamically generates resource-tailored analytical tasks, improving edge-resource utilization and reducing task-execution latency.



Future work: Deploy and evaluate RedgeX in a real-life IoT edge environment.



Observe the resources. Optimize the code. Deploy the right analytical task.